

ABSTRACT

Self-driving or Autonomous driving, Advanced Driving Assistance System (ADAS) is one of the most popular topics in research related to vehicle safety. One of the most useful technologies in autonomous driving is lane detection that uses longitudinal marks (e.g. straight and dashed lines) as a reference to keep the vehicle running on lane. Various operators on edge detection are proposed to obtain the best accuracy of lane detection. However, the movement of the line marks between frames will vary depending on the speed of the vehicle. If the system fails to detect the line marker at high speed, will cause the autonomous driving system make a wrong decision. In this final task, we will perform a comparison analysis of Sobel, Prewitt and Robert ability on edge detection methods to detect dashed line marks at varying speeds. The test results showed that all operators succeeded in achieving the minimum detection target of 80% and obtained the best operators for line marker detection is Sobel with the highest percentage at all speeds 30, 50 and 80 km / h.

Keywords: Comparison, Edge Detection, Dashed line, Speed