

## DAFTAR PUSTAKA

- [1] **Budiman, Hafid.** 2007. *Pengembangan Analitik Inverse Kinematics dan Simulasi Pergerakan Milling Robot 5 derajat kebebasan*. Program Pascasarjana. Universitas Indonesia. Jakarta.
- [2] **H. A. Park, M. A. Ali and C S. G. Lee.** 2012. *Closed-Form Inverse Kinematic Position Solution for Humanoid Robots*. International Journal of Humanoid Robotics, Vol. 9, No. 3.
- [3] **Pitowarno, Endra.** 2006. *Desain, Kontrol, dan Kecerdasan Buatan*. Yogyakarta: Penerbit ANDI.
- [4] (2006). *Dynamixel AX-12 User's Manual*, Robotis, *datasheet* diunduh dari <http://www.crustcrawler.com/products/bioloid/docs/AX-12.pdf> pada 7 Juli 2014.
- [5] (2014). *Manual DT-Sense 3D Accelerometer & Magnetometer*, STMicroelectronics Group of Companies, *datasheet* diunduh dari [http://innovativeelectronics.com/innovative\\_electronics/download\\_files/manual/Manual%20DT-Sense%203D%20Accelerometer%20Magnetometer.pdf](http://innovativeelectronics.com/innovative_electronics/download_files/manual/Manual%20DT-Sense%203D%20Accelerometer%20Magnetometer.pdf) pada 7 Juli 2014.
- [6] (2012). *Quick Start Guide The Raspberry Pi-Single Board Computer*, Element14, *datasheet* diunduh dari <http://www.farnell.com/datasheets/1524403.pdf> pada 7 Juli 2014.
- [7] (2011). *TP-LINK User Guide TL-WN725N 150Mbps Wireless N Nano USB Adapter*, TP-LINK TECHNOLOGIES, *datasheet* diunduh dari [http://www.tp-link.com/Resources/document/TL-WN725N\\_V1\\_User\\_Guide.pdf](http://www.tp-link.com/Resources/document/TL-WN725N_V1_User_Guide.pdf) pada 7 Juli 2014.