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SLAM	: Simultaneous Localization and Mapping
ROS	: Robot Operating System
3D	: 3 Dimensional
RBPF	: Rao-Blackwellized Particle Filter
SDF	: Simulation Description Format
OOP	: Object Oriented Programming
IDE	: Integrated Development Environment
PHP	: Hypertext Preprocessor
JRE	: Java Runtime Environment
RViz	: ROS Visualization
JPEG	: Joint Photographic Experts Group
PGM	: Portable Gray Map