DAFTAR PUSTAKA

[1]   L. Minh-thuan, "Study of Artificial Fish Bladder System for Robot Fish," pp. 2126–2130, 2011.

[2]   X. Wang, M. Li, W. Guo, P. Wang, and L. Sun, "Design and Development of a Cheetah Robot under the Neural Mechanism Controlling the Leg ' s Muscles *," pp. 2749–2755, 2012.

[3]   L. Vig, J. A. Adams, and S. Member, "Multi-Robot Coalition Formation," vol. 22, no. 4, pp. 637–649, 2006.

[4]   T. Dewi, P. Risma, Y. Oktarina, and M. T. Roseno, "Neural Network Controller Design for a Mobile Robot Navigation ; a Case Study," no. September, pp. 19–21, 2017.

[5]   D. L. Yoonseok Pyo, Hancheol Cho, Leon Jung, *ROS Robot Programming (English)*. 2017.

[6]   R. Illah, *Autonomous Mobile Robots*. .

[7]   J. Scholz, S. Chitta, B. Marthi, and M. Likhachev, "Cart Pushing with a Mobile Manipulation System : Towards Navigation with Moveable Objects."

[8]   A. Hornung, M. Phillips, and E. G. Jones, "Navigation in Three-Dimensional Cluttered Environments for Mobile Manipulation."

[9]   T. Foote, "tf : The Transform Library."

[10]   N. Wangsaputra and S. Teknik, "Ilustrasi Penggunaan Quaternion untuk Penanggulangan Gimbal Lock," 2016.

[11]   D. R. Wilkins, "ON QUATERNIONS , OR ON A NEW SYSTEM OF IMAGINARIES IN ALGEBRA," 2000.

[12]   N. H. Hughes, "Direction Cosine Matrix Conversion Using Geometric Methods," no. July, 2017.

[13]   G. Swalaganata, "Moving Object Tracking Using Hybrid Method," pp. 607–611, 2018.

[14]   X. Chen, X. Li, H. Wu, and T. Qiu, "Real-time Object Tracking via CamShift-Based Robust Framework," vol. 510006, pp. 0–3, 2012.

[15]   X. Guo, C. Wang, and Z. Qu, "Object tracking for autonomous mobile robot based on feedback of monocular-vision," *ICIEA 2007 2007 Second IEEE Conf. Ind. Electron. Appl.*, pp. 467–470, 2007.