

DAFTAR SINGKATAN

ROS	: <i>Robot Operating System</i>
SLAM	: Simultaneous Localization and Mapping
LIDAR	: <i>Light Detection and Ranging</i>
SBC	: <i>Single Board Computer</i>
TTL	: <i>Time To Live</i>
RPM	: <i>Revolution per Minute</i>
IMU	: <i>Inertial Measurement Unit</i>
2D	: <i>Two Dimention</i>
3D	: <i>There Dimention</i>