

## LIST OF NOTATIONS

Symbols	Definition
$s$	state
$a$	action
$s'$	expected state
$a'$	expected action
$\alpha$	learning rate
$\gamma$	discount factor
$v$	linear velocity
$\omega$	angular velocity
$W$	weight factor
$d$	distance
$a^*$	optimal action
$\epsilon$	softmax
$\pi$	policy