

**INFRARED-BASED OBSTACLE COLLISION AVOIDANCE FOR
QUADCOPTER DRONE USING FUZZY LOGIC**
**(OBSTACLE COLLISION AVOIDANCE *BERBASIS INFRARED PADA*
QUADCOPTER DRONE MEMANFAATKAN FUZZY LOGIC)**

FINAL PROJECT

Compiled as a requirement for the course of Final Project In the Bachelor of
Electrical Engineering Study Program

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