

DAFTAR SINGKATAN

YOLO	<i>You Only Look Once</i>
KITTI	<i>Karlsruhe Institute of Technology and Toyota Technological Institute</i>
3D	3 Dimensi
LiDAR	<i>Light Detection and Ranging</i>
RGB	<i>Red, Green and Blue</i>
CNN	<i>Convolutional Neural Network</i>
FPS	<i>Frames Per Second</i>
AP	<i>Average Precision</i>
mAP	<i>Mean-Average Precision</i>
TP	<i>True Positive</i>
FP	<i>False Positive</i>
FN	<i>False Negative</i>
GUI	<i>Graphical User Interface</i>