

DAFTAR GAMBAR

Gambar 2.1 Arsitektur Model Deteksi Objek	12
Gambar 2.2 Arsitektur Convolutional Neural Network (CNN) untuk Computer. 13	
Gambar 2.3 Workflow Edge Impulse Platform	17
Gambar 2.4 Arsitektur FOMO	19
Gambar 3.1 Diagram Blok Sistem	22
Gambar 3.2 Desain Perangkat Keras	24
Gambar 3.3 Flowchart Edge Impulse.....	28
Gambar 3.4 Flowchart Robot.....	29
Gambar 4.1 Keseluruhan Sistem.....	32
Gambar 4.2 Kalibrasi sensor ultrasonik	33
Gambar 4.3 Kalibrasi motor dc.....	34
Gambar 4. 4 Tahap Upload Gambar	35
Gambar 4. 5 Sampel Gambar Training dan Bounding Box Warning Sign.....	36
Gambar 4. 6 Sampel Gambar Training dan Bounding Box Right Sign.....	36
Gambar 4. 7 Sampel Gambar Training dan Bounding Box Roundabout Sign	36
Gambar 4. 8 Preprocessing	37
Gambar 4. 9 Neural Network Settings	38
Gambar 4. 10 Export Model dari Edge Impulse	40
Gambar 4. 11 Built Arduino Library.....	40
Gambar 4.12 Hasil Training Di Edge Impulse.....	41
Gambar 4.13 Feature Explorer.....	42
Gambar 4.14 Hasil Serial Monitor	44
Gambar 4.15 Hasil Serial Monitor	45
Gambar 4.16 Hasil Serial Monitor	47
Gambar 4.17 Pengujian Sistem Keseluruhan dengan Warning Sign.....	48
Gambar 4.18 Pengujian Sistem Keseluruhan dengan Turn Right Sign	49
Gambar 4.19 Pengujian Sistem Keseluruhan dengan Roundabout Sign	50
Gambar 4. 20 Create a New Project.....	61
Gambar 4. 21 Data Acquisition.....	61
Gambar 4. 22 Upload Data.....	62

Gambar 4. 23 Labeling Data	62
Gambar 4. 24 Create Impulse.....	63
Gambar 4. 25 Image Processing.....	64
Gambar 4. 26 Object Detection Setup.....	64
Gambar 4. 27 Export Model dari Edge Impulse	65
Gambar 4. 28 Built Arduino Library.....	66
Gambar 4. 29 Setup ESP32 Controller Robot.....	67