

TABLE OF FIGURES

Figure 2.1 Design Concept Solution	7
Figure 2.2 Level 2 System Capturing Data of Radar	7
Figure 2.3 FMCW Signal Modulation Illustration.....	9
Figure 2.4 Block Diagram FMCW Radar	9
Figure 2.5 Depth Estimation Transformation	10
Figure 2.6 GAN depth estimation architecture[15].....	11
Figure 2.7 Pose Estimation	12
Figure 2.8 U-Net Architecture	13
Figure 2.9 Convolutional Process	14
Figure 2.10 ReLU Graph.....	15
Figure 2.11 Pooling Illustration	15
Figure 3.1 System Design.....	16
Figure 3.2 Block Diagram Systems	16
Figure 3.3 Radar IWR6843ISK-ODS	18
Figure 3.4 DCA1000EVM.....	19
Figure 3.5 Logitech Brio 500.....	20
Figure 3.6 Flowchart Radar Signal Process	21
Figure 3.7 Flowchart Image Process.....	212
Figure 4.1 Environment capturing data: (a) Subject Height Body Tested, (b) Camera Height.....	23
Figure 4.2 Calibration Testing Measurement Sample Figures.....	24
Figure 4.3 Pose Estimation using feature extraction	25
Figure 4.4 Depth Estimation Using GAN.....	26
Figure 4.5 Generator Architecture	27
Figure 4. 6 Discriminator Architecture	27
Figure 4.7 Model Training Accuracy.....	28
Figure 4.8 Radar Configuration	29
Figure 4.9 time delayed estimation of each joints.....	29
Figure 4.10 Image to signal Radar	30
Figure 4.11 Radar Signal Spectrum	30
Figure 4.12 System Performance Spectrogram and Radar Signal.....	31