ABSTRACT

Barcode is a method of encoding text information that tends to simple and

cheap. At this time, barcode reading system applied in Indonesia is to use Infrared

Scanner. This system is felt still less in terms of flexibility and efficiency. To

answer these problems, in this thesis author tries to develop a bar code reading

system based on digital image recognition.

Data used in this thesis were taken using a digital camera. Pre-processing

is perform after getting the image, include: convert RGB images to grayscale

images, and perform edge detection. After that, the system will perform skew

detection and then image rotation to restore the image to position 0°. Then do the

pre-processing 2, namely: the acquisition of pixels that passed Scanline, calculate

the gradient of each pixel, LPF, and masking. Furthermore, the system recognition

process of reading the composition of bars and spaces is passed by the Scanline.

Then, from the reading process gained confidence value that determines the level

of confidence in reading the barcode system. Readable bar code displayed on the

screen.

Designed system is tested levels of performance on several different

conditions, namely: distance shooting, the slope of the barcode, edge detection

method is used, and type of the sample surface. Analysis parameters used are the

percentage accuracy of rotation and the percentage accuracy of reading.

From the test results obtained edge detection method are best used in this

system is the method of Sobel and Prewitt. For samples with flat surfaces this

method produce the percentage approaches 100% accuracy of the rotation at

various angles and distance shots. For accurate readings, the system can do the

reading well on a flat surface with a shooting distance of 10 cm and 20 cm, 87.5%

at a distance of 10 cm, and 83.3% at a distance of 20cm, but the accuracy of the

reading system is very bad at a distance of 30 cm, ie close 0%, so also with

samples which have curved and irregular surfaces.

Keywords: barcode, edge detection